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# Orthonormal Basis Functions For Modeling Continuous-time Fractional Systems

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# Objective

## Synthesis of fractional orthogonal basis for system identification purposes

Extending Laguerre function's definition to  
fractional orders

# Outline

- Definitions and generalities
- Synthesis of orthogonal basis function using Gram-Schmidt procedure
- Completeness of the basis
- Identification using orthogonal basis
- Conclusions and actual work

# Definitions and generalities

# Fractional systems



## Differentiation equation

$$y(t) + a_1 \left( \frac{d}{dt} \right)^{n_{a_1}} y(t) + \dots + a_L \left( \frac{d}{dt} \right)^{n_{a_L}} y(t) = b_0 \left( \frac{d}{dt} \right)^{n_{b_0}} u(t) + \dots + b_M \left( \frac{d}{dt} \right)^{n_{b_M}} u(t)$$

$n_{a_1}, n_{a_2}, \dots, n_{a_L}, n_{b_0}, n_{b_2}, \dots, n_{b_M}$  are real

## Fractional differentiation (Riemann Liouville, XIXème century)

$$D^n f(t) \stackrel{\Delta}{=} \frac{1}{\Gamma(m-n)} \left( \frac{d}{dt} \right)^m \left( \int_0^t \frac{f(\tau)}{(t-\tau)^{1-(m-n)}} d\tau \right) \quad \text{where} \quad \begin{cases} t > 0 \\ \mathcal{R}e(n) > 0 \\ m = \lfloor \mathcal{R}e(n) \rfloor + 1 \end{cases}$$

# Representation of fractional systems



## Differentiation equation

$$y(t) + a_1 \left( \frac{d}{dt} \right)^{n_{a_1}} y(t) + \dots + a_L \left( \frac{d}{dt} \right)^{n_{a_L}} y(t) = b_0 \left( \frac{d}{dt} \right)^{n_{b_0}} u(t) + \dots + b_M \left( \frac{d}{dt} \right)^{n_{b_M}} u(t)$$

$n_{a_1}, n_{a_2}, \dots, n_{a_L}, n_{b_0}, n_{b_2}, \dots, n_{b_M}$  are real

## Transfer function

$$H(s) = \frac{\mathcal{L}\{y(t)\}}{\mathcal{L}\{u(t)\}} = \frac{b_0 s^{n_{b_0}} + \dots + b_M s^{n_{b_M}}}{1 + a_1 s^{n_{a_1}} + \dots + a_L s^{n_{a_L}}}$$

# Main characteristic of fractional systems

## Example

The impulse response of:  $\frac{1}{s^n + \lambda_l}$

$$\mathcal{L}^{-1}\left(\frac{1}{s^n + \lambda_l}\right) = \underbrace{\sum_{k=1}^{\text{polesnumber}} \frac{s_k}{n\lambda_l} e^{ts_k}}_{\text{exponentials modes}} + \underbrace{\frac{\sin(n\pi)}{\pi} \int_0^\infty \frac{x^n e^{-tx}}{x^{2n} - 2\lambda_l x^n \cos(n\pi) + \lambda_l^2} dx}_{\text{aperiodic modes}}$$

exponentials modes

aperiodic modes

# Orthogonal functions

## ⊗ Orthogonality

Plancherel's theorem

$$\langle g_n, g_m \rangle = \int_0^{\infty} g_n(t)g_m(t) dt = \delta_{nm} \quad \longleftrightarrow \quad \langle G_n, G_m \rangle = \frac{1}{2\pi j} \int_{-j\infty}^{j\infty} G_n(j\omega)\overline{G_m(j\omega)} d\omega = \delta_{nm}$$

## ⊗ Mean square error

$$\|e\|^2 = \langle e, e \rangle = \int_0^{\infty} e(t)e(t) dt$$

## ⊗ In a context of system approximation

$$e(t) = f(t) - \sum_{i=1}^N a_i g_i(t)$$

$$\underline{A} = \left( \underline{g} \underline{g}^T \right)^{-1} \langle \underline{g}, f \rangle$$

$I$

## Most common orthogonal functions in control

⊗ **Laguerre functions:** Unique pole

Well suited for modeling systems with a single predominant dynamical behavior

⊗ **Kautz functions:** Two complex conjugate poles

Well suited for modeling systems having predominant oscillatory behavior

⊗ **GOB functions:** Any number of poles

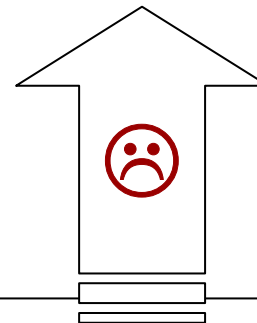
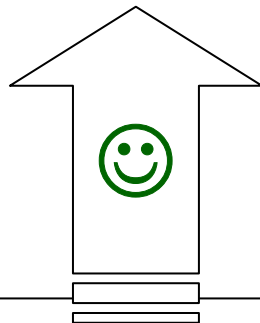
Extend the two former definitions to any number of real or complex conjugate poles

# Classical orthonormal basis

$$\mathcal{L}^{-1}\left(\frac{1}{s^n - \lambda_l}\right) = \underbrace{\sum_{k=1}^{\text{poles number}} \frac{s_k}{n\lambda_l} e^{ts_k}}_{\text{exponentials modes}} + \underbrace{\frac{\sin(n\pi)}{\pi} \int_0^\infty \frac{x^n e^{-tx}}{x^{2n} - 2\lambda_l x^n \cos(n\pi) + \lambda_l^2} dx}_{\text{aperiodic modes}}$$

exponentials modes

aperiodic modes



slow convergence  
high basis length

Laguerre, Kautz  
Generalized Orthogonal Basis

functions with integer differentiation

# Laguerre basis

⊗  $n$  integer

$$l_n(t) = \sqrt{2\lambda} \frac{e^{\lambda t}}{n!} \frac{d^n (t^n e^{-2\lambda t})}{dt^n}$$

$$L_n(s) = \sqrt{2\lambda} \frac{(s - \lambda)^n}{(s + \lambda)^{n+1}}$$

⊗ as soon as  $n$  is non-integer

$$\int_0^{\infty} (l_n(t))^2 dt = \infty$$

$$\forall n \in \mathbb{R}^+ - \mathbb{N}$$

Abbott P.C. (2000)

# Laguerre basis

## ⊠ Classical Laguerre functions

$$L_n(s) = \sqrt{2\lambda} \frac{(s - \lambda)^n}{(s + \lambda)^{n+1}}$$

⊠ can be used to approximate fractional systems  $f(t)$  iff:

$$\int_0^{\infty} (f(t))^2 dt < \infty$$

⊠ Caution! a stable fractional system can have:

$$\int_0^{\infty} (f(t))^2 dt = \infty$$

See Malti et al. (ASME'2003)

# Laguerre basis

⊗ When the fractional systems is  $L_2[0, \infty[$

$$F(s) \approx \sum_{n=0}^N L_n(s)$$

Has to be large

⊗ because:

- Fails to capture the aperiodic multimode

⊗ Idea: why not synthesizing a fractional orthogonal basis ?

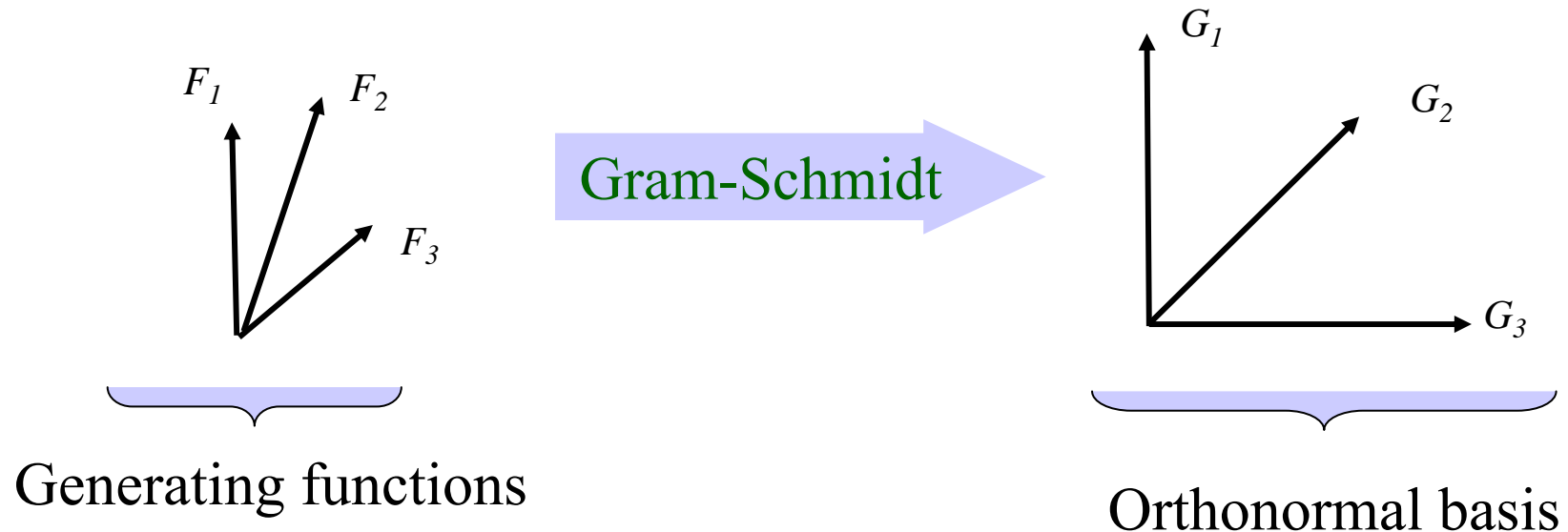


# Synthesis of a new fractional orthogonal basis

The new basis will have two tuning parameters:

- Commensurate order  $n$
- Eigenvalue  $\lambda$

# Synthesis of new basis



## Generating functions

$$F_1(s) = \frac{1}{s^n + \lambda}, F_2(s) = \frac{1}{(s^n + \lambda)^2}, \dots, F_m(s) = \frac{1}{(s^n + \lambda)^m}, \dots \quad m = 1, 2, 3, \dots$$

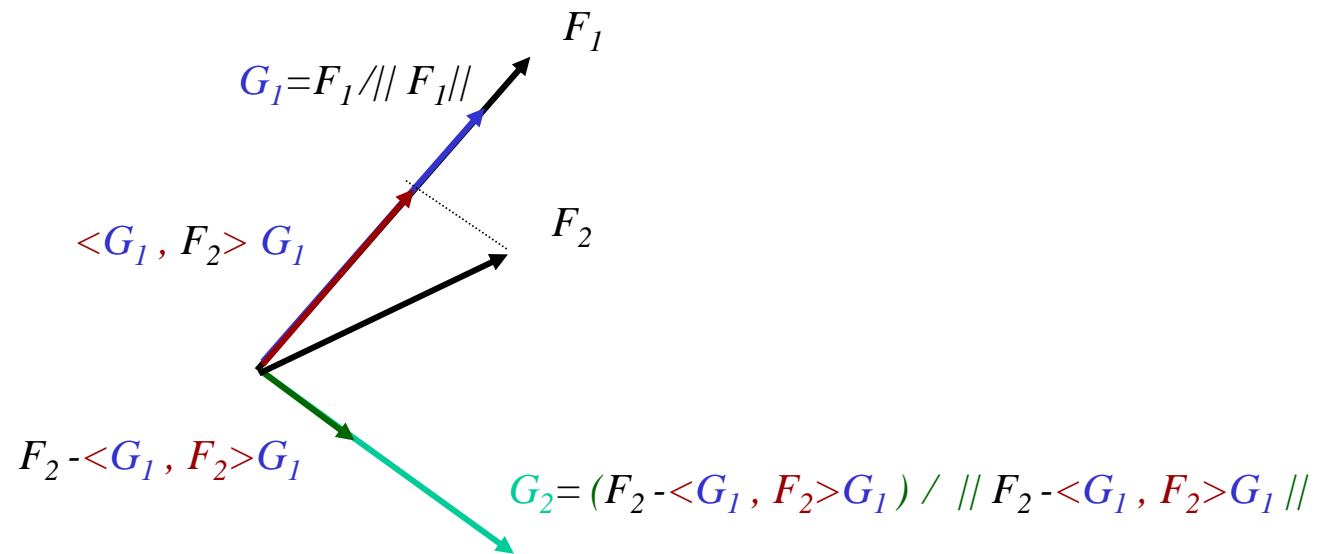
$$n > 0$$

$$\lambda > 0$$

$n$  and  $\lambda$  are the same for all the functions

# Orthogonalisation Procedure

## Gram-Schmidt procedure



### 1<sup>st</sup> basis function

$$G_1(s) = \alpha_{1,1} \frac{1}{s^n + \lambda}$$

$$\alpha_{1,1} = \left\| \frac{1}{s^n + \lambda} \right\|^{-1}$$

### 2<sup>nd</sup> basis function

$$G_2(s) = \alpha_{2,1} G_1(s) + \alpha_{2,2} F_2(s)$$

$$\langle G_1(s), G_2(s) \rangle = 0$$

$$\langle G_2(s), G_2(s) \rangle = 1$$

# Orthogonalisation Procedure

## Gram-Schmidt procedure

$$G_1(s) = \alpha_{1,1} F_1(s)$$

$$G_2(s) = \alpha_{2,1} F_1(s) + \alpha_{2,2} F_2(s)$$

## Matrix notation

$$\begin{bmatrix} G_1(s) \\ G_2(s) \\ \vdots \\ G_{M-1}(s) \\ G_M(s) \end{bmatrix} = \begin{bmatrix} \alpha_{1,1} & 0 & \cdots & 0 & 0 \\ \alpha_{2,1} & \alpha_{2,2} & & & 0 \\ & \vdots & \ddots & & \vdots \\ \alpha_{M-1,1} & \alpha_{M-1,2} & \cdots & \alpha_{M-1,M-1} & 0 \\ \alpha_{M,1} & \alpha_{M,2} & \cdots & \alpha_{M,M-1} & \alpha_{M,M} \end{bmatrix} \begin{bmatrix} F_1(s) \\ F_2(s) \\ \vdots \\ F_{M-1}(s) \\ F_M(s) \end{bmatrix} \rightarrow \underline{\mathbf{G}}(s) = \underline{\boldsymbol{\alpha}} \underline{\mathbf{F}}(s)$$

## Orthogonalisation

$$\langle \underline{\mathbf{G}}, \underline{\mathbf{G}}^T \rangle = I \quad \rightarrow \quad \underline{\boldsymbol{\alpha}} \langle \underline{\mathbf{F}}, \underline{\mathbf{F}}^T \rangle \underline{\boldsymbol{\alpha}}^T = I \quad \rightarrow \quad \underline{\boldsymbol{\alpha}} = \text{Cholesky} \left( \langle \underline{\mathbf{F}}, \underline{\mathbf{F}}^T \rangle^{-1} \right)$$

# Orthogonalisation Procedure

**Difficulty – how to compute :**  $\langle F_{m_1}, F_{m_2} \rangle$

When differentiation order is non-integer

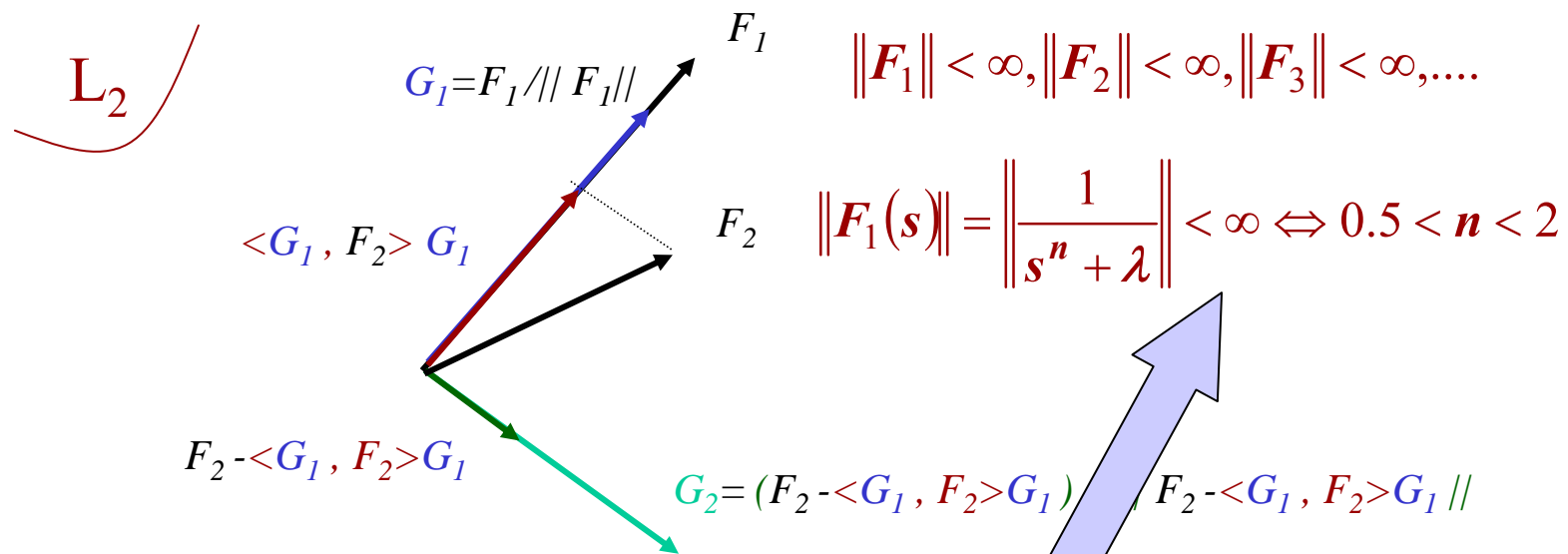
- $F_{m_1}$  and  $F_{m_2}$  are not holomorphic functions
- a plan cut is necessary between 0 and  $\infty$
- the scalar product is computed along a Bromwich-Wagner contour

The difficulty is to compute:

$$\langle F_{m_1}, F_{m_2} \rangle = \frac{1}{2\pi j} \int_{-j\omega}^{j\omega} F_{m_1}(j\omega) \overline{F_{m_2}(j\omega)} d\omega$$

# Necessary condition

## Gram-Schmidt procedure



1<sup>st</sup> basis function

$$G_1(s) = \alpha_{1,1} \frac{1}{s^n + \lambda}$$

$$\alpha_{1,1} = \left\| \frac{1}{s^n + \lambda} \right\|^{-1}$$

**necessary condition**  
 **$0.5 < n < 2$**

# Example 1

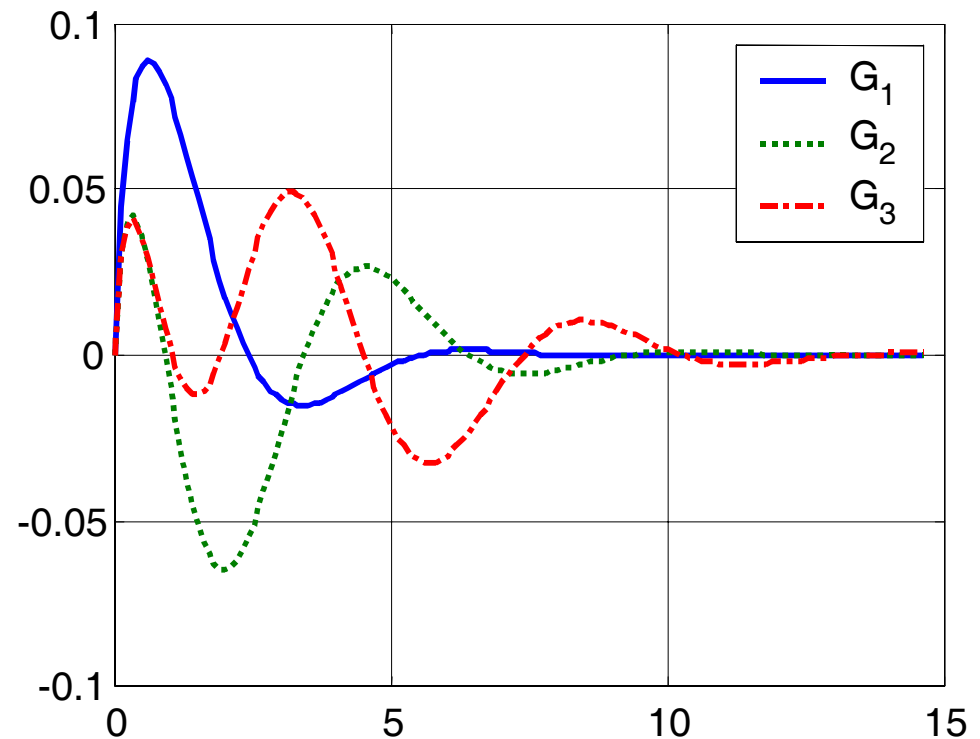
$n = 1.5, \lambda = 1.5$

$$F_1(s) = \frac{1}{s^{1.5} + 1.5}, F_2(s) = \frac{1}{(s^{1.5} + 1.5)^2}, F_3(s) = \frac{1}{(s^{1.5} + 1.5)^3}$$

$$G_1(s) = \frac{1.49}{s^{1.5} + 1.5}$$

$$G_2(s) = \frac{0.7}{s^{1.5} + 1.5} + \frac{-2.37}{(s^{1.5} + 1.5)^2}$$

$$G_3(s) = \frac{-0.12}{s^{1.5} + 1.5} + \frac{-1.17}{(s^{1.5} + 1.5)^2} + \frac{3.56}{(s^{1.5} + 1.5)^3}$$



## Example 2

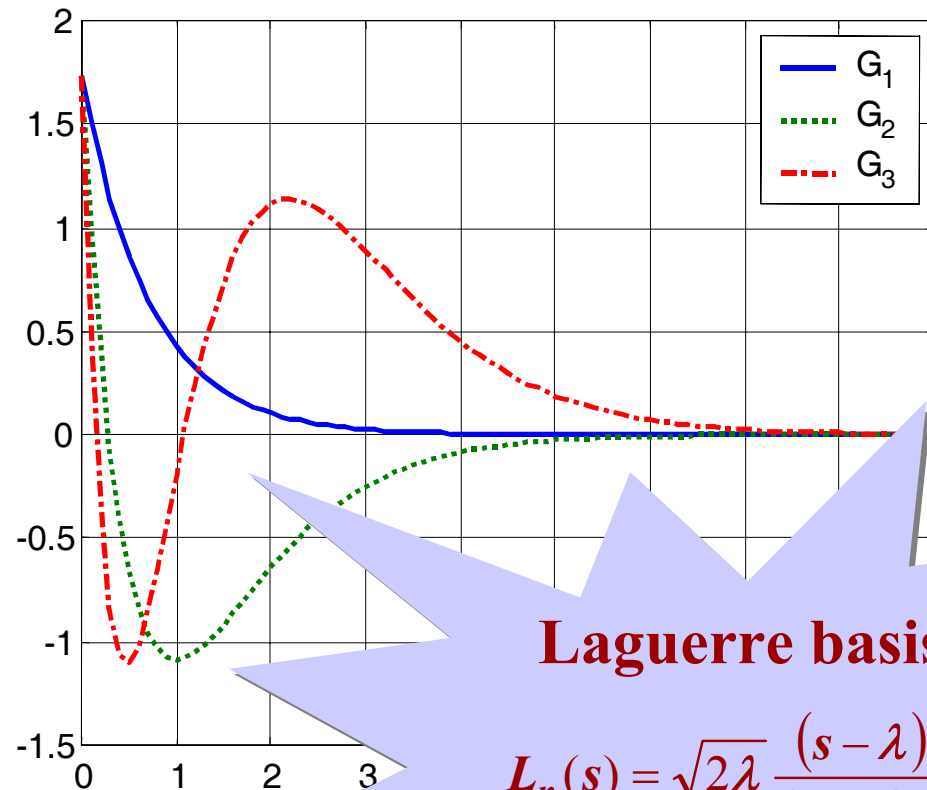
$$n = 1, \lambda = 1.5$$

$$F_1(s) = \frac{1}{s^1 + 1.5}, F_2(s) = \frac{1}{(s^1 + 1.5)^2}, F_3(s) = \frac{1}{(s^1 + 1.5)^3}$$

$$G_1(s) = \frac{\sqrt{3}}{s + 1.5}$$

$$G_2(s) = \sqrt{3} \left( \frac{1}{s + 1.5} + \frac{-3}{(s + 1.5)^2} \right) = \sqrt{3} \frac{(s - 1.5)^2}{(s + 1.5)^3}$$

$$G_3(s) = \sqrt{3} \left( \frac{1}{s + 1.5} + \frac{-6}{(s + 1.5)^2} + \frac{9}{(s + 1.5)^3} \right) \\ = \sqrt{3} \frac{(s - 1.5)^3}{(s + 1.5)^4}$$

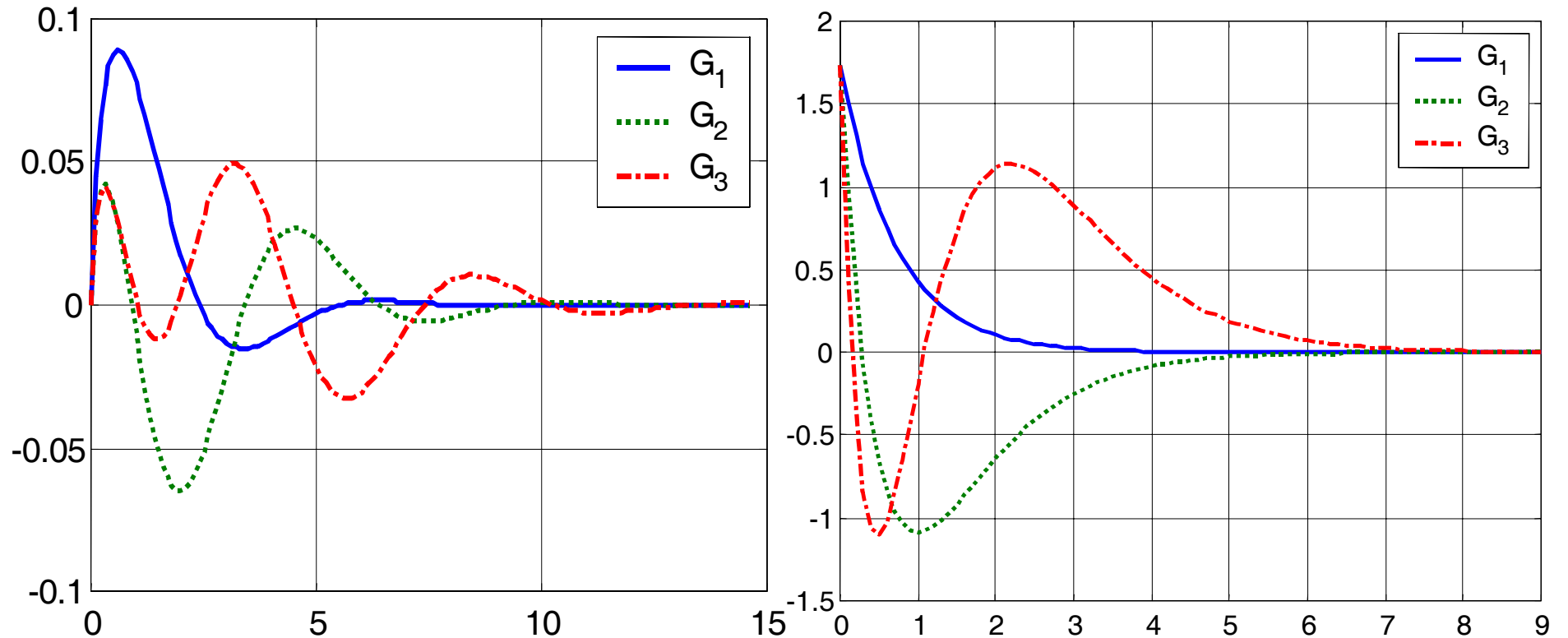


**Laguerre basis**

$$L_n(s) = \sqrt{2\lambda} \frac{(s - \lambda)^n}{(s + \lambda)^{n+1}}$$

# Fractional order effect (1)

$\lambda=1.5$

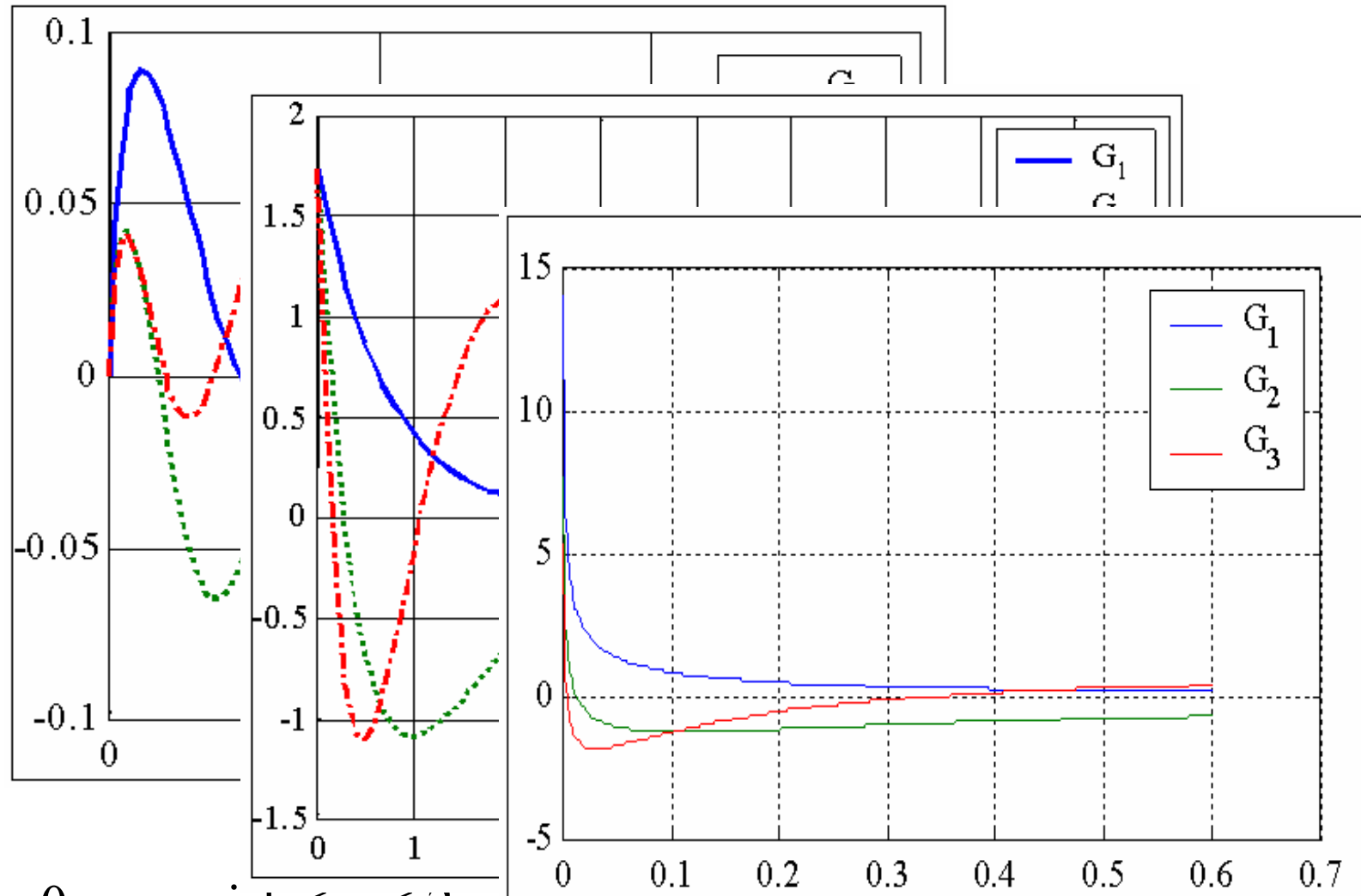


$n=1,5$

$n=1$

$n \nearrow \longleftrightarrow$  Oscillations  $\nearrow$

## Fractional order effect (2)



➤  $g_m(0) = 0$  si  $1 < n < 2$

➤  $g_m(0) = (2\lambda)^{0.5}$  si  $n = 1$  (Laguerre functions)

➤  $g_m(0) = \infty$  si  $\frac{1}{2} < n < 1$

# Completeness of the new basis

If the basis is complete then:

$$\forall f(t) \in L_2[0, \infty[ \Rightarrow f(t) = \sum_{n=0}^{\infty} a_n g_n(t)$$

# Completeness

## Theorem

$$F_1(s) = \frac{1}{(s^n + \lambda)^1}, F_2(s) = \frac{1}{(s^n + \lambda)^2}, \dots, F_m(s) = \frac{1}{(s^n + \lambda)^m}, \dots$$

The proposed orthogonal basis spans completely  $L_2[0, \infty[$  iff  
 $0.5 < n < 2$

## Extension to any commensurate order $0 < n < 2$

The proposed orthogonal basis spans completely  $L_2[0, \infty[$ , for every  
 $0 < n < 2$ , iff :

$$F_1(s) = \frac{1}{(s^n + \lambda)^k}, F_2(s) = \frac{1}{(s^n + \lambda)^{k+1}}, \dots, F_m(s) = \frac{1}{(s^n + \lambda)^m}, \dots$$

$$k > \left\lfloor \frac{1}{2n} \right\rfloor, \left\lfloor \frac{1}{2n} \right\rfloor + 1, \dots, \infty$$

# Particular case Laguerre functions

## Completeness theorem

Laguerre functions are known to span  $L_2[0, \infty[$

## Particular case of our theorem

Indeed, if  $n = 1$

$$k > \left\lfloor \frac{1}{2 \times 1} \right\rfloor = \lfloor 0.5 \rfloor = 1$$

$$F_1(s) = \frac{1}{(s^n + \lambda)^1}, F_2(s) = \frac{1}{(s^n + \lambda)^2}, \dots, F_m(s) = \frac{1}{(s^n + \lambda)^m}, \dots$$

## Extension to any commensurate order $0 < n < 2$

Take the generating functions:

$$F_1(s) = \frac{1}{(s^n + \lambda)^k}, F_2(s) = \frac{1}{(s^n + \lambda)^{k+1}}, \dots, F_m(s) = \frac{1}{(s^n + \lambda)^m}, \dots$$

Set, for example, commensurate order to 0.21, then:

$$k > \left\lfloor \frac{1}{2 \times 0.21} \right\rfloor = \lfloor 2.38 \rfloor \Rightarrow k = 3$$

Hence the generating functions are:

$$F_1(s) = \frac{1}{(s^{0.21} + \lambda)^3}, F_2(s) = \frac{1}{(s^{0.21} + \lambda)^4}, \dots, F_m(s) = \frac{1}{(s^{0.21} + \lambda)^m}, \dots$$

# **System identification using fractional orthogonal basis**

# System identification - Principe

## Model structure

$$H(s) \approx \sum_{m=1}^M g_m G_m(s)$$

$$H(s) \approx \underbrace{[g_1 \ g_2 \ \dots \ g_M]}_{\mathbf{g}} [G_1(s) \ G_2(s), \dots \ G_M(s)]^T$$

## Algorithm

Wahlberg 91

Choose  $n$  and  $\lambda$

Criterion

$$J = \frac{1}{T} \int_0^T \left( \sum_{m=1}^M g_m u_{G_m}(t) - y(t) \right)^2 dt$$

$$u_{G_m}(t) = G_m(t) \otimes u(t)$$

Optimal  $\mathbf{g}$

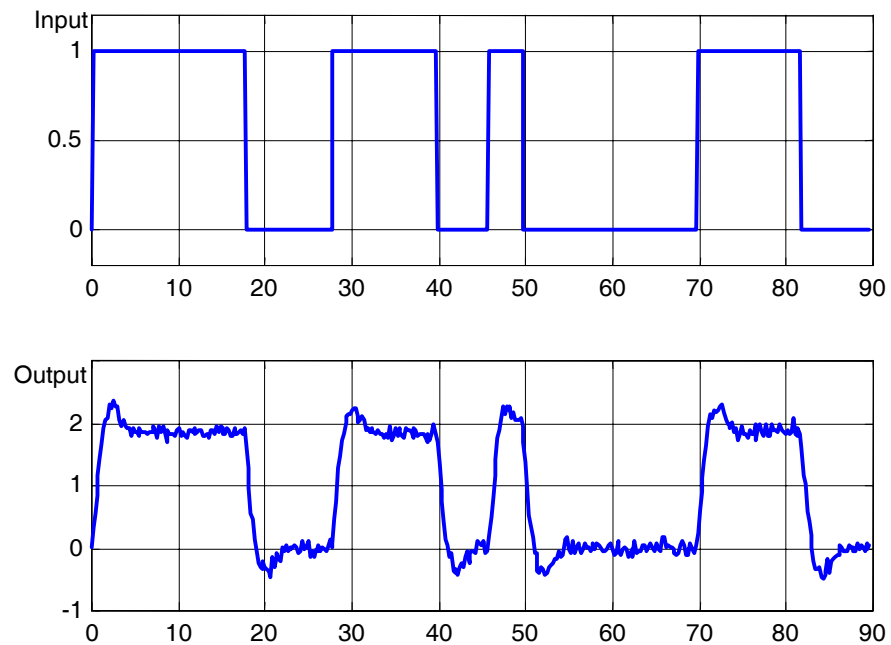
$$\hat{\mathbf{g}} = \left[ \int_0^T (\mathbf{u}_G(t)^T \mathbf{u}_G(t)) dt \right]^{-1} \int_0^T \mathbf{u}_G(t)^T y(t) dt \quad \Rightarrow \quad \hat{\mathbf{g}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

# Academic example

## Initial system

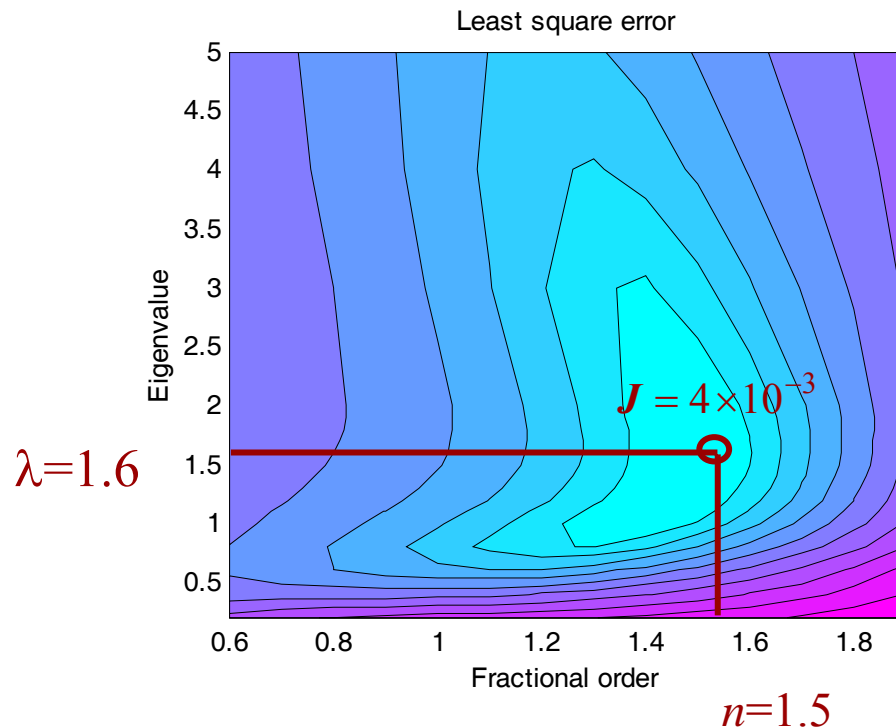
$$H(s) = \frac{1}{s^{1.5} + 1.5} + \frac{1}{s^{1.5} + 1.6} + \frac{1}{s^{1.5} + 1.8}$$

## Identification data



# Optimisation

$$H(s) = \frac{1}{s^{1.5} + 1.5} + \frac{1}{s^{1.5} + 1.6} + \frac{1}{s^{1.5} + 1.8}$$

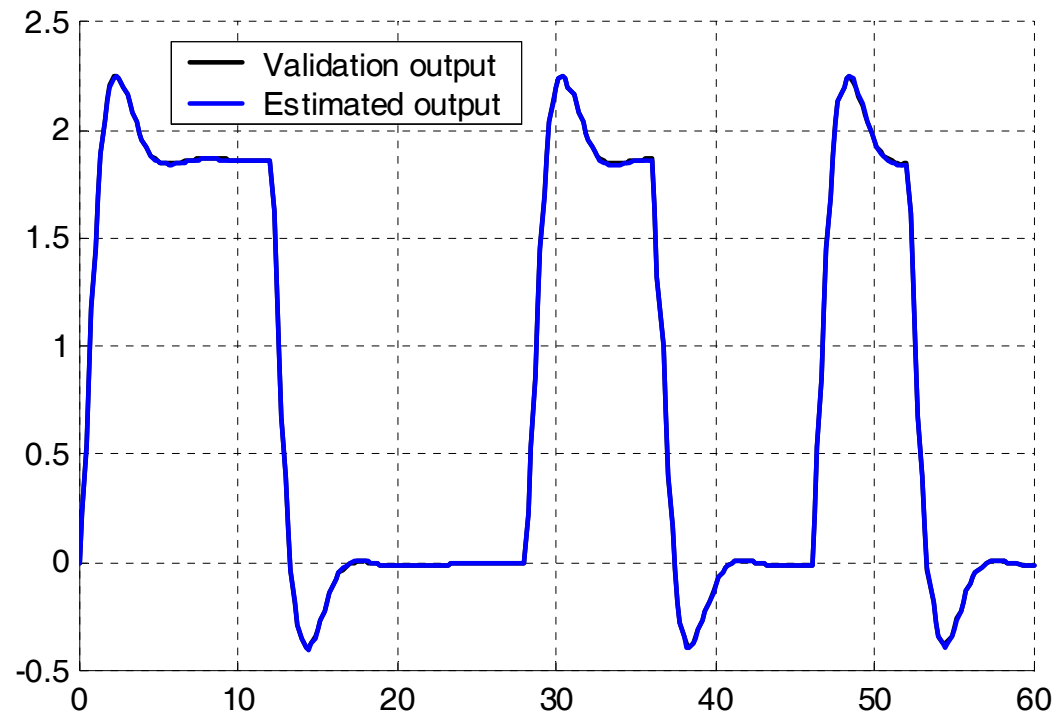


$$\hat{H}(s) = 1.89 G_1(s) - 0.01 G_2(s)$$

$$\hat{H}(s) \cong 1.48 L_1(s) - 0.94 L_2(s) - 0.54 L_3(s) + 0.44 L_4(s) + 0.22 L_5(s)$$

# Validation

## Validation data



## Conclusions

A new fractional orthonormal basis is synthesized. It has two tuning parameters:

commensurate order  $n$  and eigenvalue  $\lambda$

Most propriety used in classical identification algorithms are still valid → two tuning parameters are to be set (instead of one as in Laguerre case)

The new basis can be used in model reduction

## Recent results

The completeness of the fractional basis is proved. The completeness condition is determined. (yet to be published).

The fractional order interval is extended to  $]0, 2[$ .

Kautz and GOB functions are currently being generalized  
A paper will be proposed in FDA'04

## Problem at stake

Let:

$$F(s) = \frac{\sum_{m=0}^{m_A} a_m s^{\alpha_m}}{1 + \sum_{m=1}^{m_B} b_m s^{\beta_m}}$$

Although  $F(s)$  is stable, it has an  $\infty$   $L_2$  norm if:

$$\beta_{mB} \leq \alpha_{mA} + \frac{1}{2} \quad \text{See Malti et al. (ASME'2003)}$$

**This particular class of fractional models cannot be approximated by orthogonal functions because ...**

... the approximation is based on the minimization of the the MSE which indeed is  $\infty$ .

