

بِسْمِ اللَّهِ الرَّحْمَنِ الرَّحِيمِ

السَّلَامُ عَلَيْكُمْ وَرَحْمَةُ اللَّهِ وَبَرَكَاتُهُ




# **SOLUTION OF THE FUNDAMENTAL LINEAR FRACTIONAL ORDER DIFFERENTIAL EQUATION**

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# ***OUTLINE***

- 
- ❖ **Introduction**
  - ❖ **Relaxation Fractional Order System**
  - ❖ **Oscillation Fractional order System**
  - ❖ **Conclusion**

## Introduction

### Fundamental linear fractional order differential equation

$$(\tau_0)^m \frac{d^m x(t)}{dt^m} + x(t) = e(t) \quad , \quad \text{for } 0 < m < 2$$

### Its corresponding transfer function

$$H(s) = \frac{X(s)}{E(s)} = \frac{1}{[1 + (s\tau_0)^m]} \quad , \quad \text{for } 0 < m < 2$$

## Relaxation Fractional Order System

### Relaxation Fractional Order System

$$(\tau_0)^m \frac{d^m x(t)}{dt^m} + x(t) = e(t) \quad , \quad \text{for } 0 < m < 1$$

### Its corresponding transfer function

$$H(s) = \frac{X(s)}{E(s)} = \frac{1}{1 + (s\tau_0)^m} \quad , \quad \text{for } 0 < m < 1$$

The expansion about  $s = \infty$  using long division gives

$$H(s) = \frac{1}{1 + (s\tau_0)^m} = \frac{\tau_0^{-m}}{s^m} \sum_{n=0}^L \frac{[-(\tau_0^{-m})]^n}{s^{nm}}$$

## Relaxation Fractional Order System

$$H(s) = \frac{1}{1+(s\tau_0)^m} = \int_0^{\infty} \frac{G(\tau)}{1+s\tau} d\tau, \quad \text{for } 0 < m < 1$$

$$G(\tau) = \frac{1}{2\pi} \left[ \frac{\sin(1-m)\pi}{\left\{ \cosh \left[ m \log \left( \frac{\tau}{\tau_0} \right) \right] \right\} - \cos(1-m)\pi} \right]$$

$$H(s) = \frac{1}{1+(s\tau_0)^m} \cong \sum_{i=1}^{2N-1} \frac{G(\tau_i)}{1+s\tau_i} = \sum_{i=1}^{2N-1} \frac{k_i}{\left( 1 + \frac{s}{p_i} \right)}$$

## Relaxation Fractional Order System

where

$$k_i = G(\tau_i) = \frac{1}{2\pi} \left[ \frac{\sin[(1-m)\pi]}{\cosh[m \log(\frac{\tau_i}{\tau_0})] - \cos[(1-m)\pi]} \right]$$

$$p_i = \frac{1}{\tau_i} = (\lambda)^{(i-N)} \frac{1}{\tau_0} , \quad \text{for } i=1,2,\dots,2N-1$$

$$p_N = \frac{1}{\tau_0} = \frac{1}{\tau_N}$$

and the parameter  $\lambda$  is the sampling period

## Relaxation Fractional Order System

$$H(s) = \frac{1}{1 + (s\tau_0)^m} \cong \sum_{i=1}^{2N-1} \frac{G(\tau_i)}{1 + s\tau_i} = \sum_{i=1}^{2N-1} \frac{k_i}{\left(1 + \frac{s}{p_i}\right)}$$

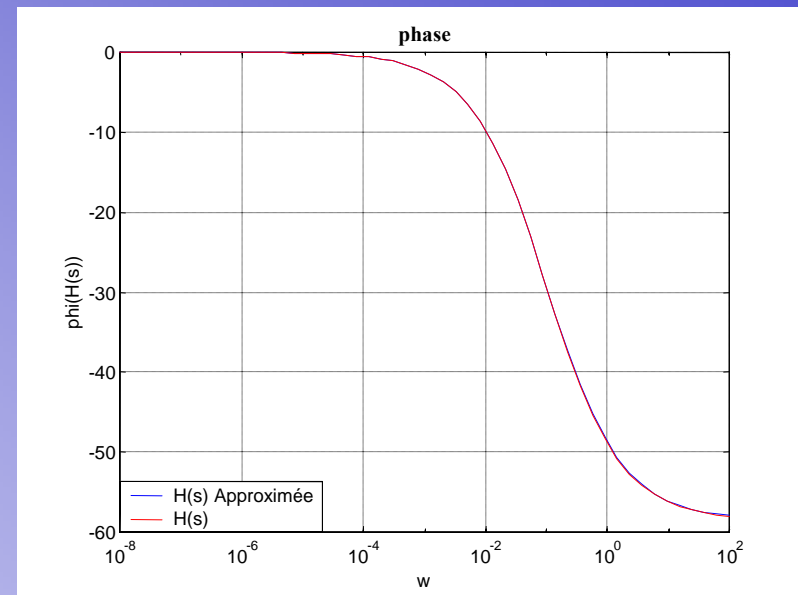
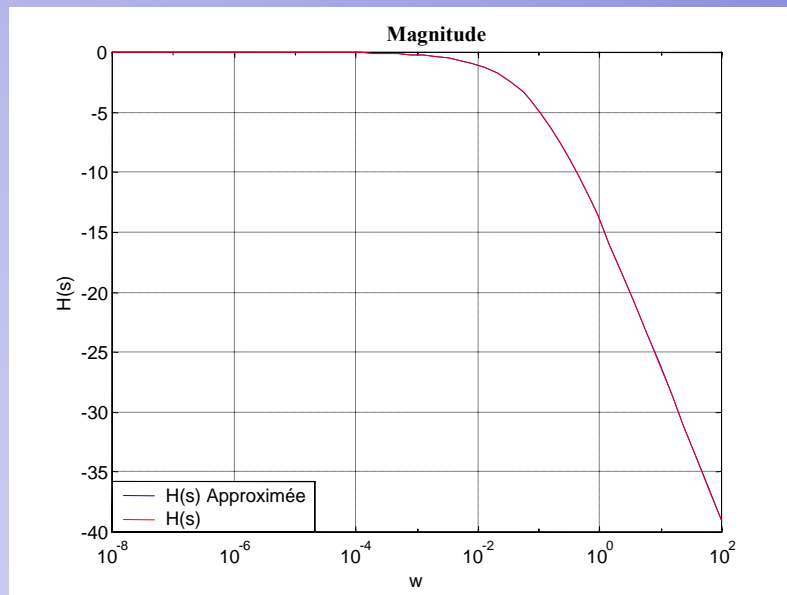
$$H(s) = \frac{1}{1 + (s\tau_0)^m} = \frac{\tau_0^{-m}}{s^m} \sum_{n=0}^L \frac{[-(\tau_0^{-m})]^n}{s^{nm}}$$

# Relaxation Fractional Order System

## Numerical example

$$(10)^{0.65} \frac{d^{0.65} y(t)}{dt^{0.65}} + y(t) = e(t)$$

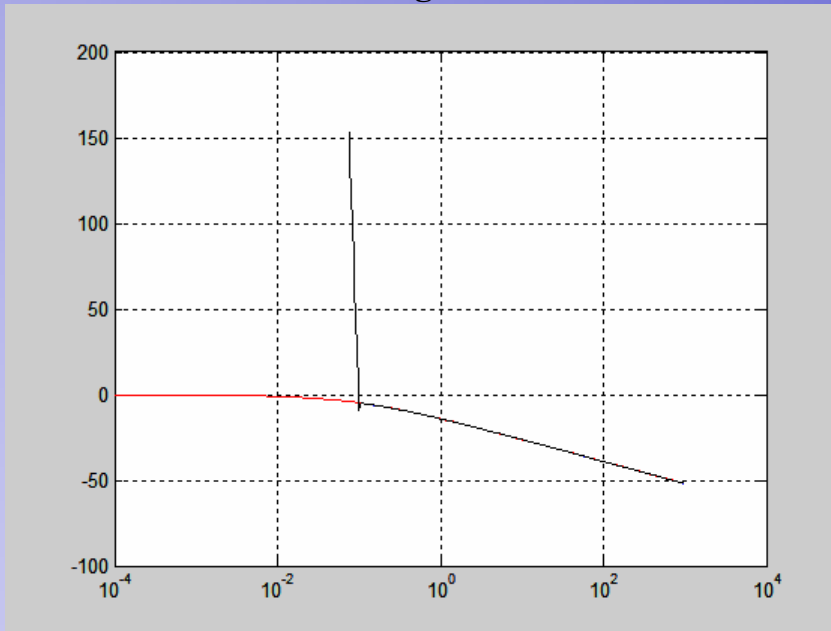
$$H(s) = \frac{1}{1 + (10s)^{0.65}}$$



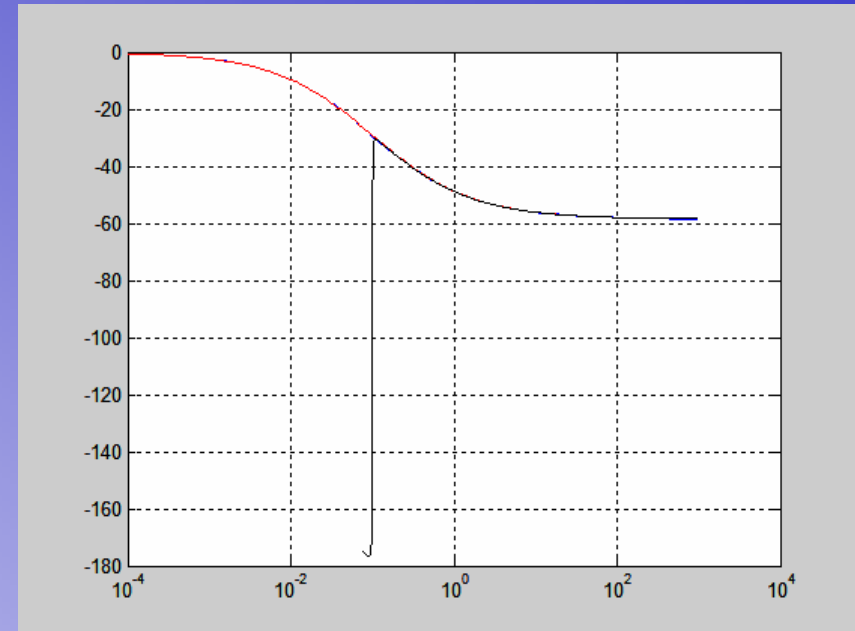
$$H(s) = \frac{1}{1 + (s\tau_0)^m} \cong \sum_{i=1}^{19} \frac{G(\tau_i)}{1 + s\tau_i} = \sum_{i=1}^{19} \frac{k_i}{\left(1 + \frac{s}{p_i}\right)}$$

# Relaxation Fractional Order System

Magnitude



Phase



$$H(s) = \frac{1}{1 + (s\tau_0)^m} = \frac{\tau_0^{-m}}{s^m} \sum_{n=0}^{100} \frac{[-(\tau_0^{-m})]^n}{s^{nm}}$$

## Relaxation Fractional Order System

Impulse response

$$h(t) = \sum_{i=1}^{2N-1} \left( \frac{k_i}{\tau_i} \exp(-t / \tau_i) \right)$$

$$h(t) = (\tau_0^{-m}) t^{(m-1)} \sum_{n=0}^L \frac{(-(\tau_0^{-m}))^n t^{nm}}{\Gamma(nm+m)}$$

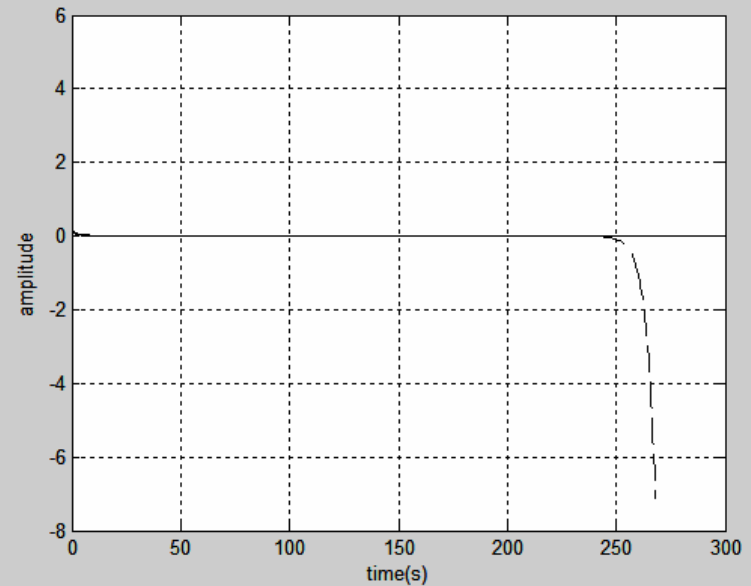
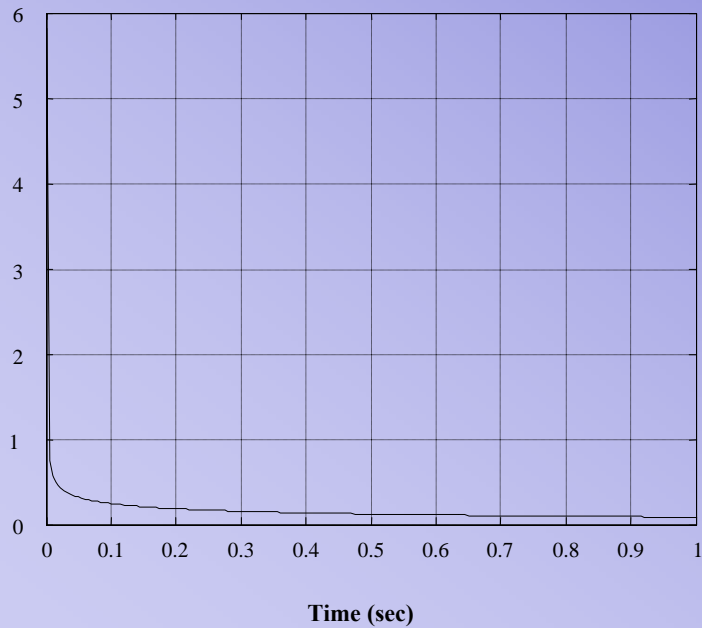
# Relaxation Fractional Order System

## Numerical example

$$(10)^{0.65} \frac{d^{0.65} y(t)}{dt^{0.65}} + y(t) = e(t)$$

$$H(s) = \frac{1}{1 + (10s)^{0.65}}$$

**N=10 and L=100**



## Relaxation Fractional Order System

Step response

$$Y(s) = \frac{1}{s[1+(s\tau_0)^m]} \cong \sum_{i=1}^{2N-1} \frac{G(\tau_i)}{s(1+s\tau_i)} = \sum_{i=1}^{2N-1} \frac{k_i}{s \left( 1 + \frac{s}{p_i} \right)}$$

$$Y(s) = \frac{1}{s[1+(s\tau_0)^m]} = \frac{1}{s} \left( \frac{\tau_0^{-m}}{s^m} \sum_{n=0}^{\infty} \frac{[-(\tau_0^{-m})]^n}{s^{nm}} \right)$$

## Relaxation Fractional Order System

$$y(t) = \sum_{i=1}^{2N-1} k_i \left( 1 - \exp(-t / \tau_i) \right)$$

$$y(t) = 1 - \sum_{n=0}^L \frac{(-(\tau_0^{-m}))^n t^{nm}}{\Gamma(nm + 1)}$$

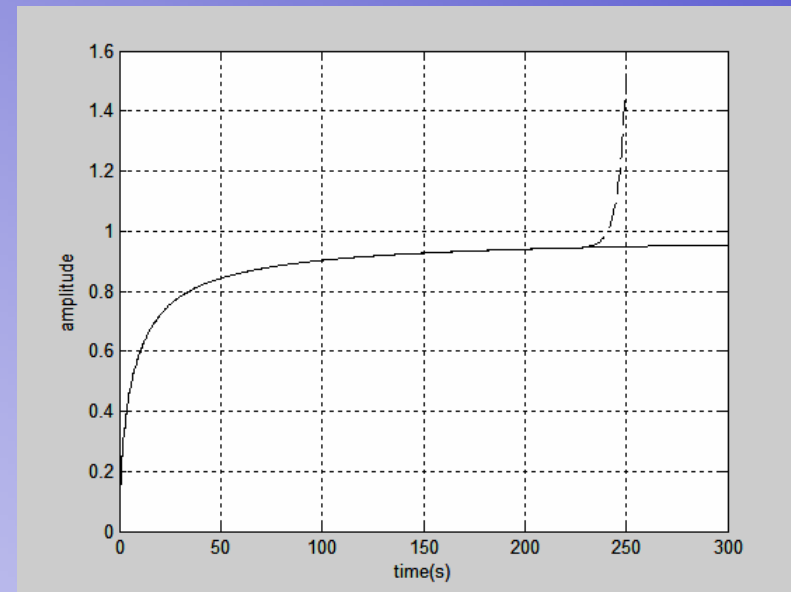
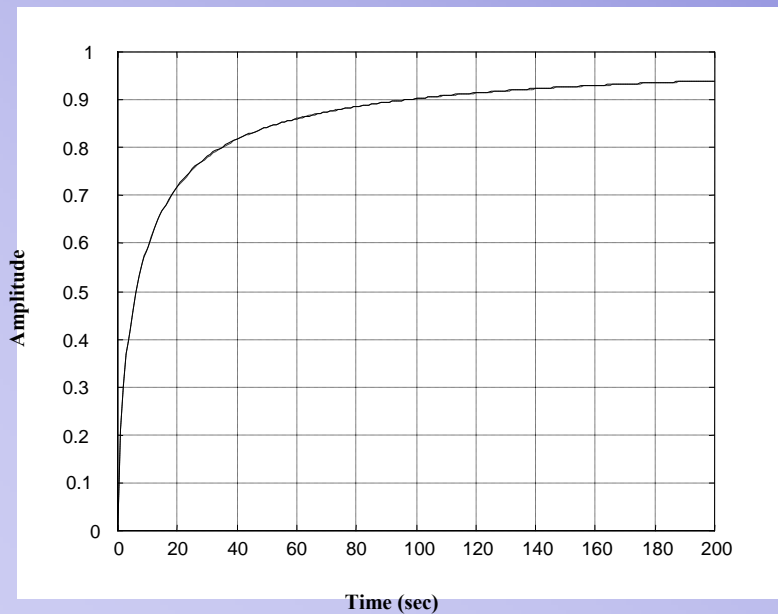
# Relaxation Fractional Order System

## Numerical example

$$(10)^{0.65} \frac{d^{0.65} y(t)}{dt^{0.65}} + y(t) = e(t)$$

$$H(s) = \frac{1}{1 + (10s)^{0.65}}$$

**N=10 and L=100**



## Oscillation Fractional Order System

### Oscillation Fractional Order System

$$(\tau_0)^m \frac{d^m x(t)}{dt^m} + x(t) = e(t) \quad , \quad \text{for } 1 < m < 2$$

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## Oscillation Fractional Order System

$$H(s) = \frac{1}{1 + (s\tau_0)^m} \approx \frac{(1 + s\tau_0)^{2-m}}{(s\tau_0)^2 + 2\xi(s\tau_0) + 1}, \text{ for } 1 < m < 2$$

**With**

$$\xi = \sqrt{\frac{[1 + \cos(\frac{\pi}{2}m)]}{2^{m-1}}}$$

**And**

$$(1 + s\tau_0)^{2-m} = \frac{\prod_{i=0}^N (1 + \frac{s}{z_i})}{\prod_{i=0}^N (1 + \frac{s}{p_i})}$$

**Because  $0 < (2-m) < 1$**

## Oscillation Fractional Order System

$$H(s) = \frac{1}{1 + (s\tau_0)^m} \approx \frac{1}{(s\tau_0)^2 + 2\xi(s\tau_0) + 1} \frac{\prod_{i=0}^N \left(1 + \frac{s}{z_i}\right)}{\prod_{i=0}^N \left(1 + \frac{s}{p_i}\right)}$$

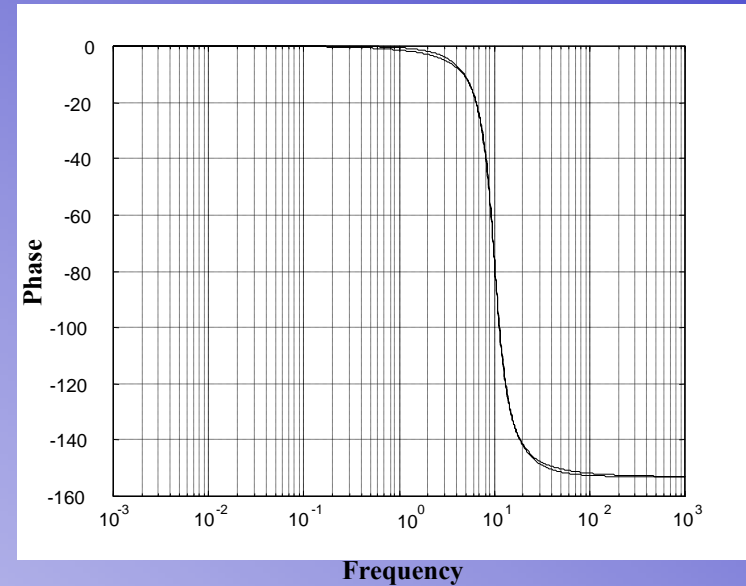
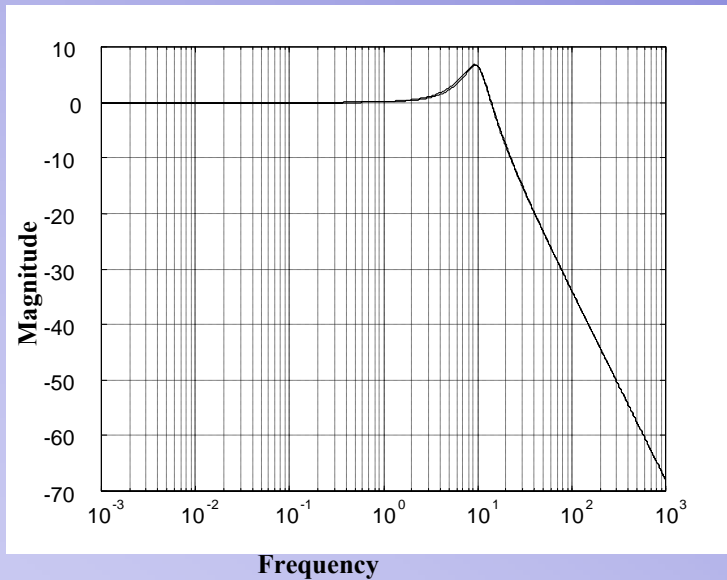
$$H(s) = \frac{As + B}{(\tau_0 s)^2 + 2\xi(\tau_0 s) + 1} + \sum_{n=0}^N \frac{k_i}{1 + \frac{s}{p_i}}$$

# Oscillation Fractional Order System

## Numerical example

$$(0.1)^{1.7} \frac{d^{1.7} x(t)}{dt^{1.7}} + x(t) = e(t)$$

$$H(s) = \frac{1}{1 + (0.1s)^{1.7}}$$



$$H(s) = \frac{As + B}{(\tau_0 s)^2 + 2\xi(\tau_0 s) + 1} + \sum_{n=0}^9 \frac{k_i}{1 + \frac{s}{p_i}}$$

## Oscillation Fractional Order System

$$H(s) = \frac{1}{1 + (s\tau_0)^m} = \frac{\tau_0^{-m}}{s^m} \sum_{n=0}^{100} \frac{[-(\tau_0^{-m})]^n}{s^{nm}}$$

## Oscillation Fractional Order System

### Impulse response

$$h(t) = \tau_0 \left( \frac{B^2 - 2AB\xi\tau_0^{-1} + A^2\tau_0^{-2}}{1 - \xi^2} \right)^{1/2} e^{-\xi\tau_0^{-1}t} \sin(\tau_0^{-1} \sqrt{(1 - \xi^2)}t + \varphi)$$

$$+ \sum_{i=0}^N k_i p_i e^{-p_i t}$$

$$h(t) = (\tau_0^{-m}) t^{(m-1)} \sum_{n=0}^L \frac{(-(\tau_0^{-m}))^n t^{nm}}{\Gamma(nm + m)}$$

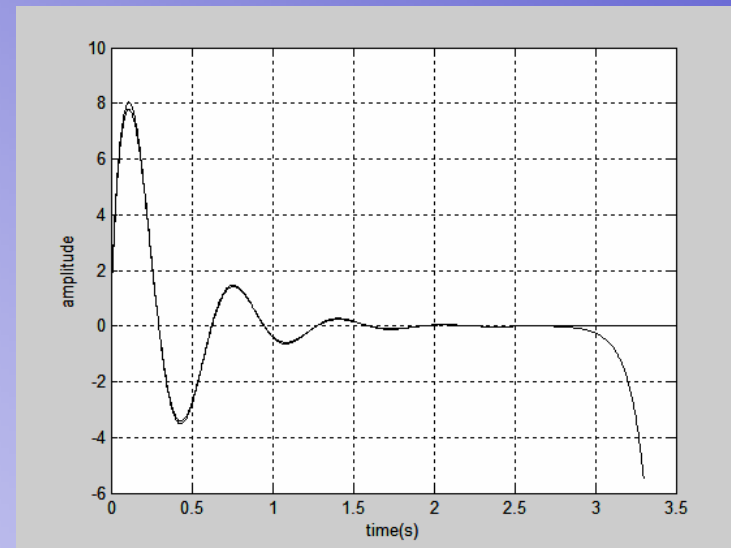
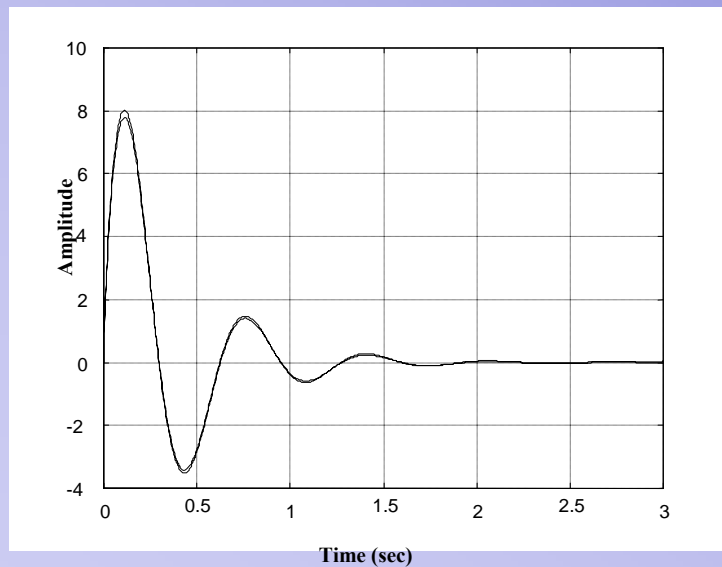
# Oscillation Fractional Order System

## Numerical example

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**N=9 and L=100**



## Oscillation Fractional Order System

Step response

$$Y(s) = \frac{1}{s[1+(s\tau_0)^m]} = \frac{1}{s} \frac{As+B}{(\tau_0 s)^2 + 2\xi(\tau_0 s) + 1} + \sum_{n=0}^N \frac{1}{s} \frac{k_i}{1 + \frac{s}{p_i}}$$

$$Y(s) = \frac{1}{s[1+(s\tau_0)^m]} = \frac{1}{s} \left( \frac{\tau_0^{-m}}{s^m} \sum_{n=0}^{\infty} \frac{[-(\tau_0^{-m})]^n}{s^{nm}} \right)$$

## Oscillation Fractional Order System

$$y(t) = 1 + \tau_0 \left( \frac{B^2 - 2AB\xi\tau_0^{-1} + A^2\tau_0^{-2}}{1 - \xi^2} \right)^{1/2} e^{-\xi\tau_0^{-1}t} \sin(\tau_0^{-1} \sqrt{(1 - \xi^2)}t + \varphi_1)$$

$$- \sum_{i=0}^N k_i p_i e^{-p_i t}$$

$$y(t) = 1 - \sum_{n=0}^L \frac{(-(\tau_0^{-m}))^n t^{nm}}{\Gamma(nm + 1)}$$

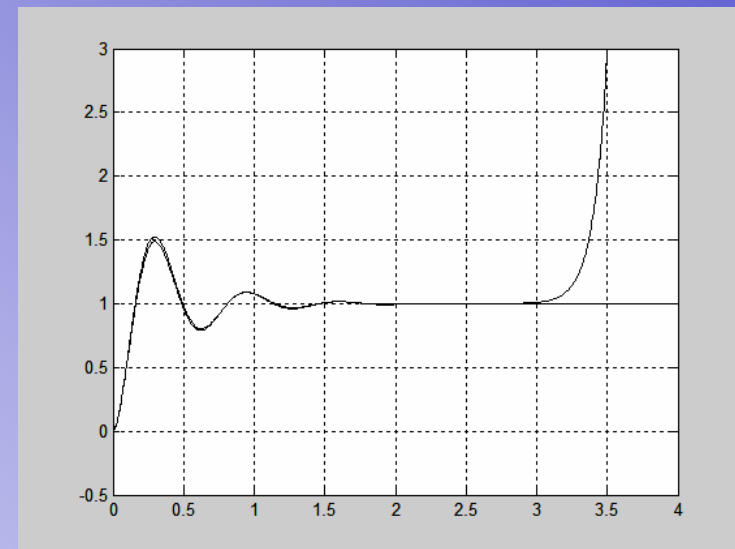
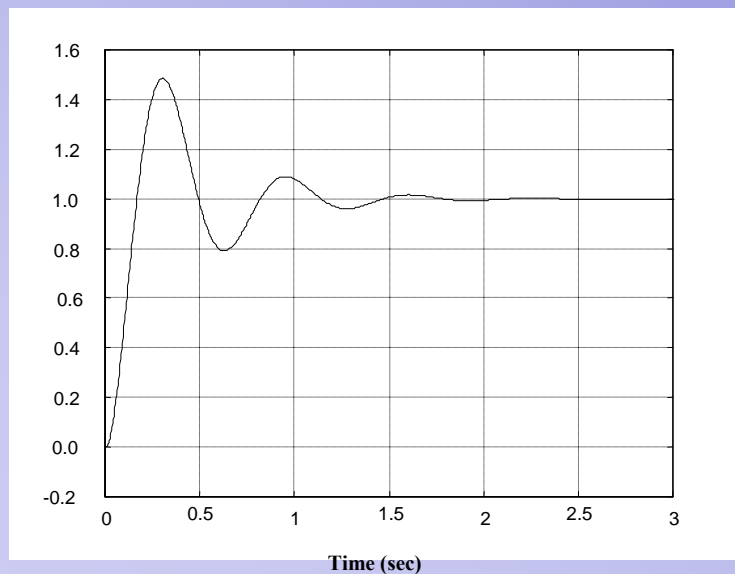
# Oscillation Fractional Order System

## Numerical example

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$$H(s) = \frac{1}{1 + (0.1s)^{1.7}}$$

**N=9 and L=100**





## Conclusion

**An effective methods for approximating the irrational transfer function the fundamental linear fractional order differential equation by a rational function, in a given frequency band is derived.**

**The impulse and step responses of this type of systems are derived.**

**Illustrative examples have been treated to demonstrate the usefulness of the approximation methods.**



## Conclusion

**These approximations can very suitable for analysis, realization and implementation of fractional order systems.**

**The expressions for characteristics and usual time and frequency specifications can also be derived.**

**The approximation presented is better than the expansion about  $s = \infty$  using long division which is shown to diverge in the time domain.**

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## Conclusion

*Thank you for your attention*